Particle Image Velocimetry (PIV)

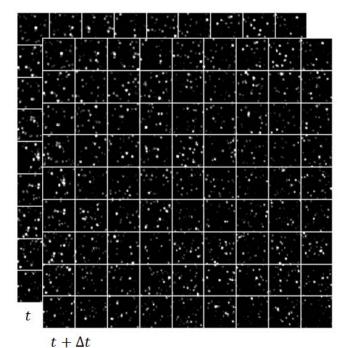


Quantitative Flow Visualization

Measurement Region Particle image velocimetry is a laser-based imaging technique that combines the accuracy of non-intrusive point measurements Small tracer particles are added to the flow with the global flow imaging capability of flow visualization to • Light is scattered from the tracer particles in the light-sheet obtain time-resolved, instantaneous velocity information over The measurement region, called Field of View $FoV = \frac{P_1 \cdot P_2}{M}$ (FoV), increases with pixel resolution:* an extended region of the flow. Illumination **The Camera System** A laser beam is formed into a light-sheet using a combination of lenses • A camera captures an image of the The light-sheet is pulsed, "freezing" particles in the light-sheet the location of particles in the planar • The magnification (M) is determined measurement region by the camera lens • The laser pulses are separated Two images are taken - one corresponding by a known time (Δt) to each laser pulse Images are transferred to a computer for processing Spatial resolution increases with magnification • Temporal resolution increases with image capture rate **PIV Results** Instantaneous planar velocity vector fields Higher-order quantities such as vorticity, shear stress, Q-criterion, and turbulent energy A sequence of images can provide temporal flow characteristics (flow evolution) **Processing Algorithms** • Images are divided into many small "interrogation windows" • Particle motion (Δx , Δy) between images is determined through cross-correlation Velocity is found by dividing the particle displacements by the time between pulses $C(\Delta x) = \int I_1(x)I_2(x + \Delta x) dx$

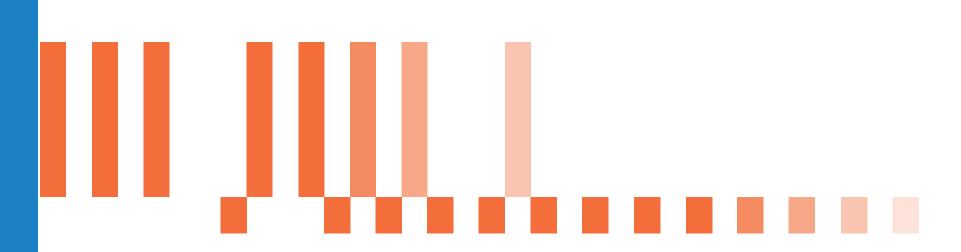
Extensions of the Technique

- StereoPIV Two cameras at oblique angles can be used to obtain 3D velocity information in a plane
- Volumetric 3-Component Velocimetry (V3V) -Three cameras are used to determine 3D velocity fields in a volume
- A high speed camera and laser can be used to obtain time resolved velocity fields



 $u = \Delta x/M \Delta t$ $v = \Delta y/M \Delta t$

• The process is repeated for all interrogation windows to obtain the instantaneous velocity field



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